

```

void faz_circulo(){

    int i,d,b;

    printf("Fazendo curva...\n");
    d=0;
    for (i=0; i < 81; i+=5){
        if(d<13){

            motor(1,d);
        }
        motor(3,i);
        d+=4;
        msleep(25L);
    }
    // motor(1,65);
    motor(1,12);
    sleep(11.3);
    d=12;

    for (; i >-1; i-=5){

        if(d>-1){

            motor(1,d);
        }
        motor(3,i);
        msleep(25L);
        d-=2;
    }
    motor(3,0);
    motor(1,0);
    // for(d=0; d<11; d+=2){
    //motor(3,d);
    // msleep(25L);
    //}
}

void LEDs(){

    float Tempo;
    int LED;
    poke(0x1009, 0x3c);
    while(!stop_button()){

        LED = random(4);
        switch (LED){

            case 0: poke(0x1008,0x04);
            break;
            case 1: poke(0x1008,0x08);
            break;
            case 2: poke(0x1008,0x20);
            break;
            case 3: poke(0x1008,0x10);
            break;
        }
        Tempo = seconds();
        while(seconds()-Tempo < 0.5){

            poke(0x1008,0x01);
        }
    }
}

int stats=0;
void LEDsT(){

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int LED;
poke(0x1009, 0x3c);
while(1 && stats==1){
    LED=random(2);
    switch(LED){
        case 0:
            poke(0x1008,0x08);
            sleep(1.0);
            break;
        case 1:
            poke(0x1008, 0x20);
            sleep(1.0);
            break;
    }
}

```

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void faz_curva(){
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int i,d,b;

printf("Fazendo curva...\n");
for (i=0; i < 96; i+=5){

    d=0;

    if(d<16){motor(3,d);}

    motor(1,i);
    msleep(25L);
    d+=4;
}
motor(3,16);

sleep(0.5);
motor(3,0);
motor(1,0);

```

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}
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void faz_curva2(){
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int i;

printf("Turning...\n");

i=0;
while (i <73){
    i += 3;
    motor(3,i);
    motor(1,-i);
    msleep(54L);
}
sleep(1.0);

printf("Stopping...\n");
while (i >0){
    i -= 4;
    motor(3,i);
    motor(1,-i);
}

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    msleep(50L);
}
motor(3,0);
motor(1,0);
}
```

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void faz_circulo20{
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```
    int i;
    int a=0;
    int b=0;

    printf("Fazendo curva...\n");
    for (i=0; i < 80;){

        b+=5;
        a+=5;

        if(b<=20){
            motor(1,b);
        }
        motor(3,a);

        msleep(25L);
    }
}
```

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void anda_reto(){
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```
    int i,b;

    printf("Moving Forward...\n");
    for (i=0; i < 52;){
        b=i-1;
        motor(3,b);
        motor(1,i);
        i += 3;
        msleep(50L);
    }
    sleep(1.0);
    printf("Stopping...\n");
    for (; i > 0;{
        i -= 3;
        b=i+1;
        motor(3,b);
        motor(1,i);
        msleep(50L);
    }

    motor(3,0);
    motor(1,0);
}
```

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}
```

```
void faz_quadrado(){
```

```
    int i;
    int b;
    int c;
```

```
c=0;
```

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i = 0;

for(c=0;c<4;c++){
    printf("Moving Forward...\n");
    for (i=0; i < 52;){
        b=i;
        motor(3,b);
        motor(1,i);
        i += 3;
        msleep(50L);
    }

    printf("Stopping...\n");
    for (; i > 0;){
        i -= 3;
        b=i;
        motor(3,b);
        motor(1,i);
        msleep(50L);
    }

    motor(3,0);
    motor(1,0);

    printf("Turning...\n");

    i=0;
    while (i <73){
        i += 3;
        motor(3,i);
        motor(1,-i);
        msleep(24L);
    }

    printf("Stopping...\n");
    while (i >0){
        i -= 4;
        motor(3,i);
        motor(1,-i);
        msleep(24L);
    }

    motor(3,0);
    motor(1,0);
}
}

int stopCount=0;
void stop_count(){
    printf("faz_quadrado()\n");
    while(1){
        while(!stop_button());
        while(stop_button());
        stopCount=(stopCount+1)%2;

        switch(stopCount){
            case 0:
                printf("faz_quadrado()\n");
                break;
            case 1:
                printf("faz_circulo()\n");
                break;
        }
    }
}

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        }
    }

void main(){
    printf("KiLegalQP-III\n");
    poke(0x1009, 0x3c);
    poke(0x1008, 0x00);

    start_process(stop_count());
    while(1){
        while(!start_button());
        while(start_button());

        switch(stopCount){

            case 0:
                stats=1;
                start_process(LEDsT());
                faz_quadrado();
                faz_quadrado();
                faz_quadrado();
                stats=0;
                poke(0x1008, 0x00);
                printf("faz_quadrado()\n");
                break;

            case 1:
                stats=1;
                start_process(LEDsT());
                faz_circulo();
                stats=0;
                poke(0x1008, 0x00);
                printf("faz_circulo()\n");
                break;
        }
    }
}

```